## Continuous eigenvalues for Meyer sets.

#### Mauricio Allendes This is a join work with Daniel Coronel.

September 21, 2017

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- 2. Preliminaries.

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## Introduction.

 Let D ⊂ ℝ<sup>d</sup> be an aperiodic Delone set and (X<sub>D</sub>, ℝ<sup>d</sup>, μ) be its associated dynamical system with μ an ergodic measure. In that follows, we denote X<sub>D0</sub> the canonical transversal and the groupoid associated by

$$\mathcal{G}_{\mathbb{R}^d} := \{ (x,t) \in X_{D_0} \times \mathbb{R}^d | x-t \in X_{D_0} \}.$$

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- When D is repetitive, X<sub>D0</sub> is a Cantor set and (X<sub>D</sub>, ℝ<sup>d</sup>, μ) is minimal.
- $\alpha \in \mathbb{R}^d$  is an eigenvalue for  $(X_D, \mathbb{R}^d, \mu)$  if exists  $f \in L^2(X_D, \mu)$ such that for  $\mu$ -almost every  $x \in X_D$  and all  $t \in \mathbb{R}^d$  is verifies

$$f(x-t) = e^{2\pi i \langle \alpha, t \rangle} f(x).$$

If *f* is continuous, then we say that  $\alpha$  is a continuous eigenvalue.

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#### Theorem

In  $\mathbb{R}^d$ , a repetitive Delone set of finite local complexity has *d* linearly independent continuous eigenvalues if and only if it is topologically conjugate to a Meyer set.

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- In particular, each repetitive Meyer set has *d* linearly independent continuous eigenvalues.
- We are interested in to find some condition to ensure that all eigenvalues are continuous. Before that, we give a dynamical proof of the fact that a Meyer set has *d* linearly independent continuous eigenvalues.

• If *D* is repetitive and  $\vec{0} \in D$ , then the abelian group [*D*] is finitely generated.

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- When the number of generators is *s* ≥ *d* we say that the rank of *D* is *s* and we write *rank*(*D*) = *s*.

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- When the number of generators is *s* ≥ *d* we say that the rank of *D* is *s* and we write *rank*(*D*) = *s*.
- Fix a basis  $\{v_1, \ldots, v_s\} \subset \mathbb{R}^d$  of [D], i.e.  $[D] = \mathbb{Z}[v_1, \ldots, v_s]$ . The address map of D is  $\phi_D : [D] \to \mathbb{Z}^s$  defined for

$$t = \sum_{i=1}^{s} n_i v_i$$
 by  $\phi_D(t) = (n_1, \dots, n_s).$ 

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$$t = \sum_{i=1}^{s} n_i v_i$$
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• If in addition, *D* is Meyer then there exists a linear map  $L_D : \mathbb{R}^d \to \mathbb{R}^s$  and a constant  $\xi_D > 0$  that verifies for all  $t \in [D]$ ,

$$\|\phi_D(t) - L_D(t)\|_s \le \xi_D.$$

• If *D* is repetitive then for all  $x \in X_{D_0}$  we have [x] = [D].

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- If *D* is repetitive then for all  $x \in X_{D_0}$  we have [x] = [D].
- Its possible to define the maps  $\Phi, L: \mathcal{G}_{\mathbb{R}^d} \to \mathbb{R}^s$  by

 $\Phi(x,t) = \phi_x(t)$  and  $L(x,t) = L_x(t)$ .

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The map L is independent in his first coordinate, i.e. for all (x, t), (y, t) ∈ G<sub>ℝ<sup>d</sup></sub> we have

$$L_x(t) = L_y(t).$$

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• The map  $\Phi - L : \mathcal{G}_{\mathbb{R}^d} \to \mathbb{R}^s$  is a continuous cocycle.

### Result in any dimension.

 If we call A ∈ M<sub>s×d</sub>(ℝ) the matrix, in canonical basis, associated to the linear transformation L, then we have the following result.

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#### Theorem (A)

Let  $D \subset \mathbb{R}^d$  be a repetitive Meyer set with rank(D) = s. The dynamical system  $(X_D, \mathbb{R}^d)$  has  $s \ge d$  continuous eigenvalues given by the rows of A.

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• Sketch of proof: For all  $x \in X_{D_0}$  consider the fiber

$$\mathcal{G}_{\mathbb{R}^d,x} := \{t \in \mathbb{R}^d : (x,t) \in \mathcal{G}_{\mathbb{R}^d}\}.$$

For all  $x \in X_{D_0}$ , the set  $(\Phi - L)(\mathcal{G}_{\mathbb{R}^d,x})$  is relatively compact.

$$\Phi(x,t) - L(x,t) = F \circ r(x,t) - F \circ d(x,t).$$

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$$\Phi(x,t) - L(x,t) = F \circ r(x,t) - F \circ d(x,t).$$

 taking exponential in each coordinate, on both sides of the last equality and considering that Φ(x, t) = φ<sub>x</sub>(t) ∈ Z<sup>s</sup>,

$$\exp(2\pi i F_i(x-t)) = \exp(-2\pi i \langle A_{i,\cdot}, t \rangle) \, \exp(2\pi i F_i(x)),$$

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where  $F_i$  is the projection in the *i*-coordinate for *F*.

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• So, we can extend the map  $f(x) = \exp(2\pi i F_i(x))$  to whole the hull for obtain an eigenfunction for the eigenvalue  $-A_{i,..}$ 

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- So, we can extend the map  $f(x) = \exp(2\pi i F_i(x))$  to whole the hull for obtain an eigenfunction for the eigenvalue  $-A_{i,..}$
- We conclude that for all *i* ∈ {1,...,*s*}, the vector −*A<sub>i</sub>*, is a continuous eigenvalue for (*X<sub>D</sub>*, ℝ<sup>d</sup>).

### Results in one dimension.

• Consider a primitive and recognizable fusion rule

 $\mathcal{F} = \{F_n(j)/1 \le j \le J_n\}_{n \in \mathbb{N}}$ 

with associated matrices  $\{M(n)\}_{n \in \mathbb{N}}$ . Denote

 $P(n) = M(n)M(n-1)\cdots M(1)$  and  $H(n) = (h_n(l): 1 \le l \le J_n)^t$ .

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#### Proposition

Let  $\mathcal{F}$  be a linearly recurrent, strongly primitive, recognizable fusion rule with FLC. Consider  $\mu$  being the unique ergodic measure for  $(X_{\mathcal{F}}, \mathbb{R})$ . If  $\alpha \in \mathbb{R}$  is an eigenvalue of  $(X_{\mathcal{F}}, \mathbb{R}, \mu)$ , then

$$\lim_{n\to\infty}\max_{1\leq k\leq J_n}\left|e^{2\pi i\alpha\cdot h_n(k)}-1\right|^2=0.$$

• For every linearly repetitive Meyer set we can associate a fusion rule that is linearly recurrent and strongly primitive. Using this we obtain the following result.

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#### Theorem (B)

Consider  $D \subset \mathbb{R}$  a linearly repetitive Meyer set such that the associated fusion rule is recognizable. Suppose that for all  $m \ge 1$  the heights  $h_m(1), \ldots, h_m(J_m)$  are rationally independent. Then  $(X_D, \mathbb{R})$  has only continuous eigenvalues.

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Sketch of proof: Using the previous proposition if *α* is an eigenvalue, then exist *m* ∈ N and a family of integers (*w<sub>j</sub>*)<sub>1≤j≤J<sub>m</sub></sub> such that

$$\alpha = \sum_{j=1}^{J_{\tilde{m}}} w_j \ \mu_0(C_{F_{\tilde{m}}(j)}).$$

Where  $C_{F_n(j)}$  is the set of all tilings in  $X_{D_0}$  such that the origin is positioned at the control point of the *n*-tile  $F_n(j)$ .

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Since *D* is a repetitive and Meyer set, the sets
*D<sub>n</sub>* = {*t* ∈ ℝ/*D* − *t* ∈ *A<sub>n</sub>*} are also repetitive and Meyer sets and verifies

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• So, for all  $n > \tilde{m}$  and every  $1 \le j \le J_n$  exist  $t_{1,j}, t_{2,j} \in D_n \subset D_{\tilde{m}}$  with  $t_{1,j} > t_{2,j}$  such that  $h_n(j) = t_{1,j} - t_{2,j}$  and therefore

$$\phi_{D_{\tilde{m}}-t_{2,j}}(h_n(j)) = [P_{j,\cdot}(n,\tilde{m})]^t.$$

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$$\phi_{D_{\tilde{m}}-t_{2,j}}(h_n(j)) = [P_{j,\cdot}(n,\tilde{m})]^t.$$

• For this reason, for all  $n > \tilde{m}$  and every  $1 \le j \le J_n$  we have

$$\left\|\frac{1}{h_n(j)}[P_{j,\cdot}(n,m_0)]^t - \mathcal{L}_{D_{m_0}}(1)\right\|_{s} \leq \frac{\xi_{D_{m_0}}}{h_n(j)}.$$

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• If we denote 
$$\mu(\tilde{m}) = \begin{bmatrix} \mu_0(C_{F_{\tilde{m}}(1)}) \\ \vdots \\ \mu_0(C_{F_{J_{\tilde{m}}}(J_{\tilde{m}})}) \end{bmatrix}$$
, where  $\mu_0$  is the transversal measure, we have

$$\|\mathcal{L}_{D_{\tilde{m}}}(1) - \mu(\tilde{m})\|_{s} \leq \left\|\frac{[P_{j,\cdot}(n,\tilde{m})]^{t}}{h_{n}(j)} - \mathcal{L}_{D_{\tilde{m}}}(1)\right\|_{s} + \left\|\frac{[P_{j,\cdot}(n,\tilde{m})]^{t}}{h_{n}(j)} - \mu(\tilde{m})\right\|_{s}$$

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Taking n→∞, we have L<sub>Dm</sub>(1) = μ(m̃) and by the theorem (A), we conclude that for all 1 ≤ i ≤ Jm̃, α' = μ<sub>0</sub>(C<sub>Fm̃(i)</sub>) is a continuous eigenvalue of (X<sub>Dm̃</sub>, ℝ).

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- Since  $(X_{D_{\tilde{m}}}, \mathbb{R})$  is a factor of  $(X_D, \mathbb{R})$  we conclude the result.

## Examples 1.

A sequence s = (s<sub>i</sub>)<sub>i∈Z</sub> ∈ {0,...,m}<sup>Z</sup> is almost linear if there exist a finite collection of real number {γ<sub>a</sub>}<sup>m</sup><sub>a=0</sub> and some constant C such that the partial sums

$$S_i(a) := \begin{cases} \sum_{k=0}^{i-1} \mathbb{1}_{\{a\}}(s_k) & \text{if } i \ge 1, \\ 0 & \text{if } i = 0, \\ \sum_{k=i}^{-1} \mathbb{1}_{\{a\}}(s_k) & \text{if } i \le -1 \end{cases}$$

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satisfy for all  $i \in \mathbb{Z}$ ,  $\max_{0 \le a \le m} |S_i(a) - i \operatorname{sign}(i) \gamma_a| \le C$ .

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#### Theorem (Lagarias, 1999.)

If  $s = (s_i)_{i \in \mathbb{Z}} \in \{0, ..., m\}^{\mathbb{Z}}$  is an almost linear sequence, then for all finite collection of rationally independent positive numbers  $\alpha_0, ..., \alpha_m$  the Delone set  $D_{\alpha_0,...,\alpha_m}(s)$  is Meyer.

• As a consequence of theorem (B), we have.

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#### Theorem

Let  $s = (s_i)_{i \in \mathbb{Z}} \in \{0, ..., m\}^{\mathbb{Z}}$  be a symbol sequence that is almost linear and such that  $(X_{D_{\alpha_0,...,\alpha_m}(s)}, \mathbb{R})$  is linearly recurrent. Suppose that the associated fusion rule is recognizable and for all  $n \ge 1$  the heights  $h_1(n), ..., h_{c(n)}(n)$  are rationally independent, then the transversal system  $(X_{D_{\alpha_0,...,\alpha_m}(s)}, \mathbb{R})$  has only continuous eigenvalues.

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 Also, using theorem (A), we can observe that for all 1 ≤ k ≤ m the real numbers

$$\beta_0 = \frac{m\gamma_1 - 1}{m\gamma_1(\alpha_0 - \alpha_1) - \alpha_0}$$
 and  $\beta_k = \frac{m\gamma_k}{m\gamma_k(\alpha_k - \alpha_0) + \alpha_0}$ 

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are continuous eigenvalue of  $(X_{D_{\alpha_0,...,\alpha_m}(s)}, \mathbb{R})$ .

• Define the substitutions  $\sigma_A, \sigma_B : \{1, 2\} \rightarrow \{1, 2\}^*$  by

$$\sigma_A : \begin{cases} \sigma_A(1) = 2211111 \\ \sigma_A(2) = 22211 \end{cases}$$
 and  $\sigma_B : \begin{cases} \sigma_B(1) = 211 \\ \sigma_B(2) = 21. \end{cases}$ 

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• Consider the sequence  $(v_n)_{n \in \mathbb{N}} \subset \mathbb{R}$  inductively by  $v_1 = 1$  and

$$v_{n+1} = \begin{cases} \beta_A v_n & \text{; if } nv_n \le 1\\ \beta_B v_n & \text{; if } nv_n > 1. \end{cases}$$

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Define a fusion rule with tiles of level *n* defined by the substitutions σ<sub>1</sub> = I and σ<sub>n+1</sub> = σ<sub>n</sub> ∘ σ<sub>M(n)</sub>, where

$$M(n+1) = \begin{cases} A & \text{; if } nv_n \le 1\\ B & \text{; if } nv_n > 1. \end{cases}$$

• Define the substitutions  $\sigma_A, \sigma_B : \{1, 2\} \rightarrow \{1, 2\}^*$  by

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• Define a fusion rule with tiles of level *n* defined by the substitutions  $\sigma_1 = \mathbb{I}$  and  $\sigma_{n+1} = \sigma_n \circ \sigma_{M(n)}$ , where

$$M(n+1) = \begin{cases} A & \text{; if } nv_n \le 1\\ B & \text{; if } nv_n > 1. \end{cases}$$

This fusion rules allows us construct a sequence η ∈ {1,2}<sup>ℤ</sup> that is not almost linear.

Associating lenghts to tile the real line we obtain

• If the vector of initial lenghts are  $H(1) = \begin{pmatrix} 1 \\ \phi \end{pmatrix}$ , the dynamical system  $(X_{\eta}, \mathbb{R})$  has only to 0 as a continuous eigenvalue and the set of eigenvalues is given by

$$E = \left\{ e^{2\pi i \alpha} \in \mathbb{C}; \ \alpha = \left(\frac{1}{2}, \frac{\phi - 1}{2}\right) \cdot A^{-l} w, \ l \ge 0, \ w \in \mathbb{Z}^2 \right\}$$

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• If the vector of initial lenghts are  $H(1) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ , the dynamical system  $(X_{\eta}, \mathbb{R})$  has eigenvalues given by

$$E = \mathbb{Z} \cup \left\{ e^{2\pi i \alpha} \in \mathbb{C}; \ \alpha = \left(\frac{2\phi - 1}{5}, \frac{3 - \phi}{5}\right) \cdot A^{-l} w, \ l \ge 0, \ w \in \mathbb{Z}^2 \right\}$$

Where the only continuous eigenvalues are  $\alpha \in \mathbb{Z}$ .

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